

Building Tracking Detector Modules for P2

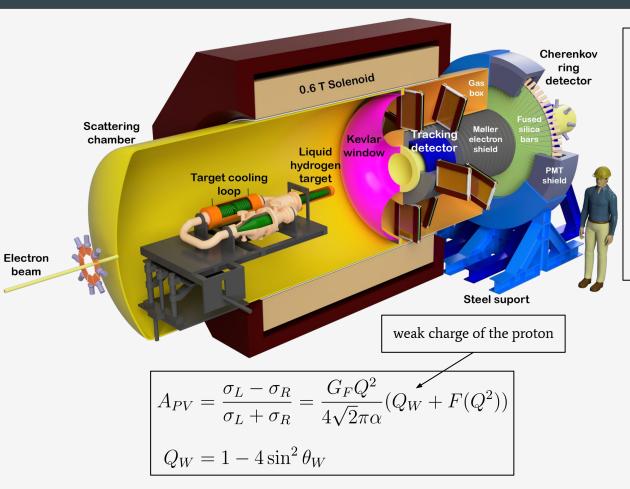
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KPH-Meet-up 09-05-2023 Lucas Sebastian Binn AG Berger Niklaus Berger, Philipp Kern, Michail Kravchenko, Lars Steffen Weinstock

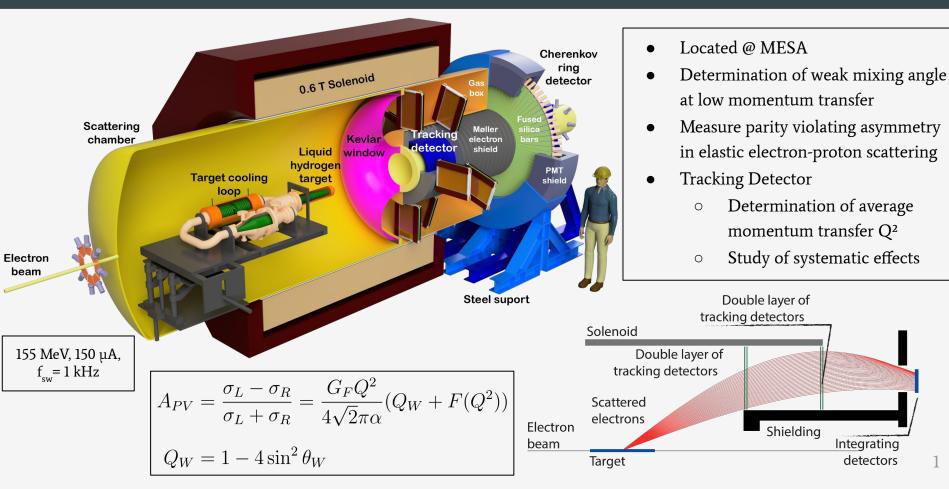


P2 Experiment

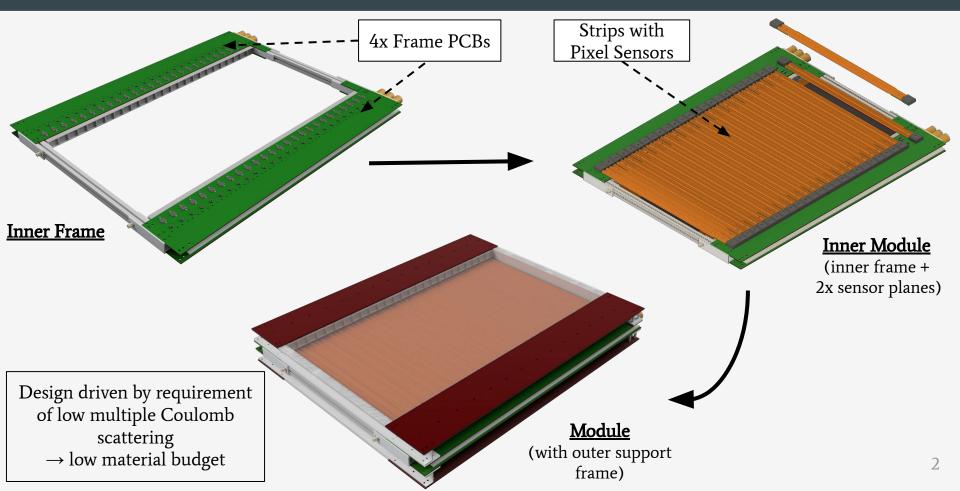


- Located @ MESA
- Determination of weak mixing angle at low momentum transfer
- Measure parity violating asymmetry in elastic electron-proton scattering

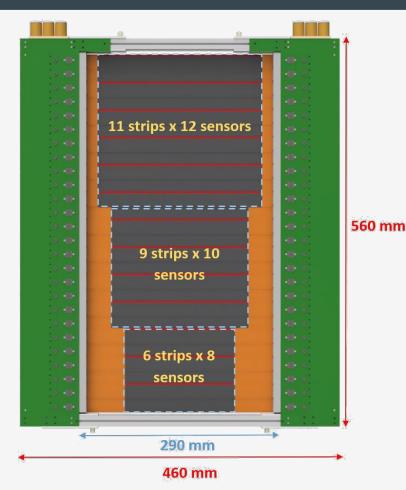
P2 Experiment



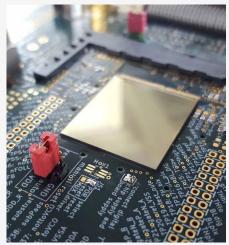
Tracking Detector Module



Strip Configurations & Sensors

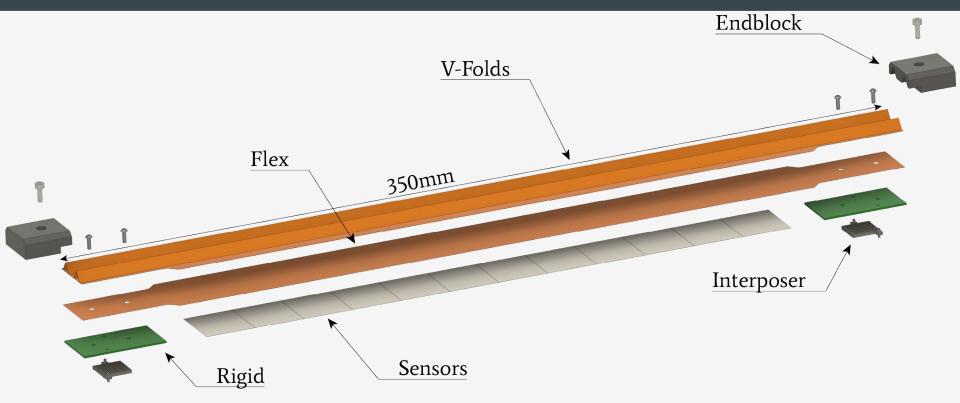


- 540 pixel sensors per module
- Similar pixel sensors as used in the Mu3e experiment
 → knowledge in group
- Monolithic, 70 µm thickness
 - \rightarrow reduced material budget
 - \rightarrow reduced multiple Coulomb scattering

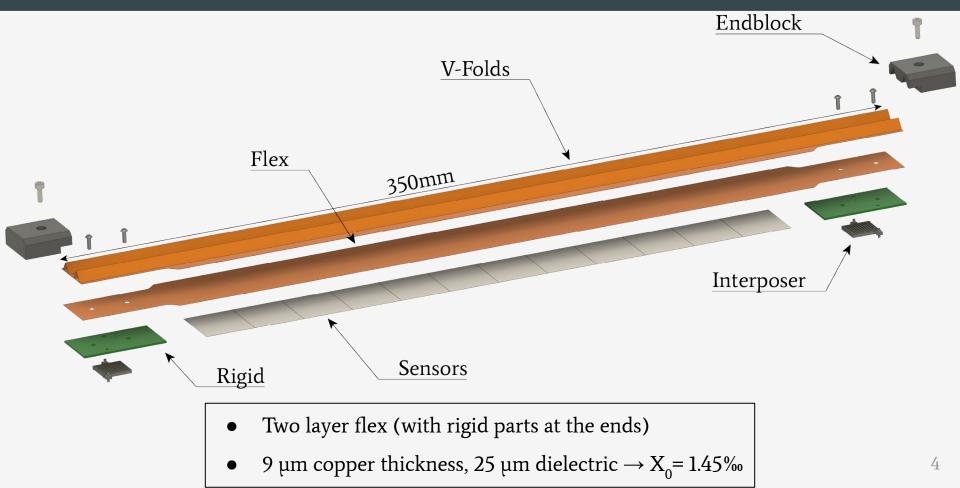


[MuPix 10]

Structure of the Strips



Structure of the Strips



Development of Rigid-Flex

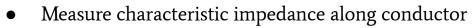
Soldered Rigid-Flex

<u>Rigid-Flex</u>

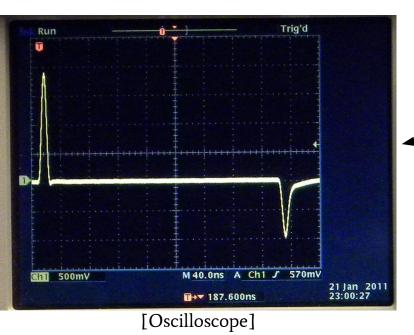


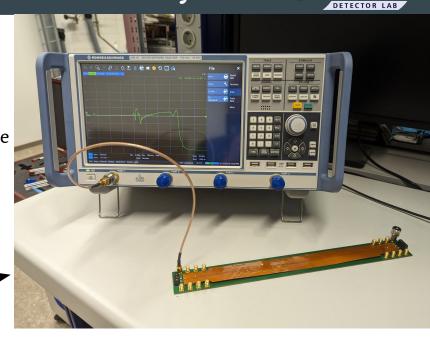
Test Jig (with mounted rigid-flex)



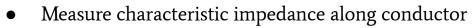


- Verify differential line impedance (constant) (signal integrity @ 1.25 Gbit/s)
- Reflection of signal at change of characteristic impedance

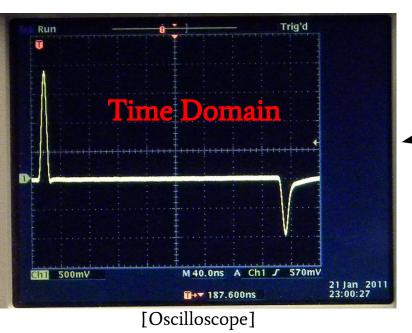


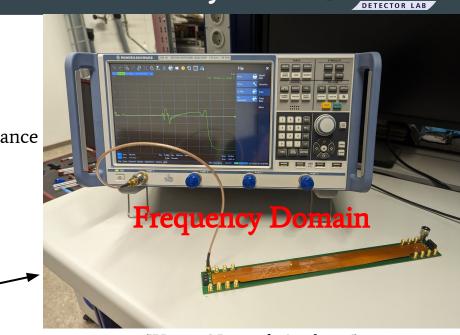


DFT



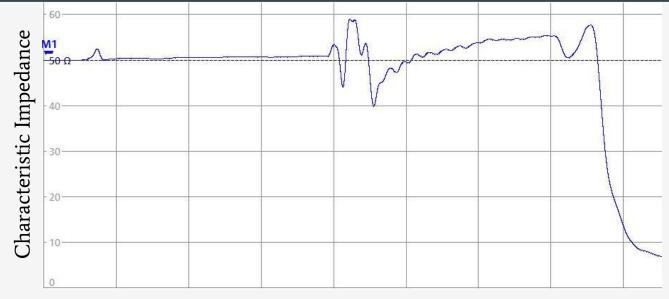
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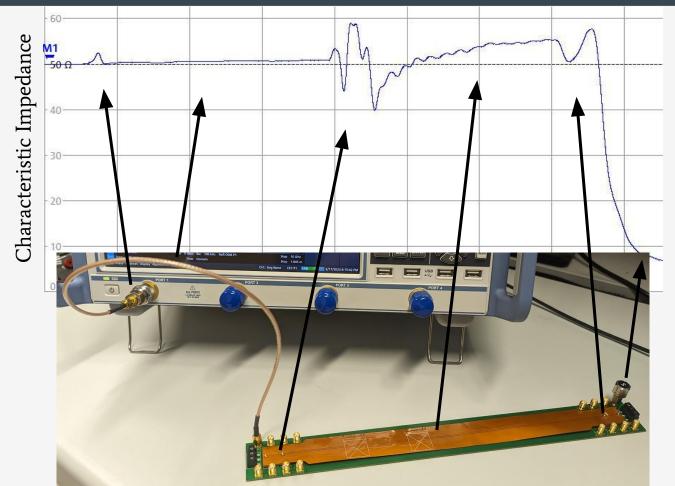
[Vector Network Analyser]



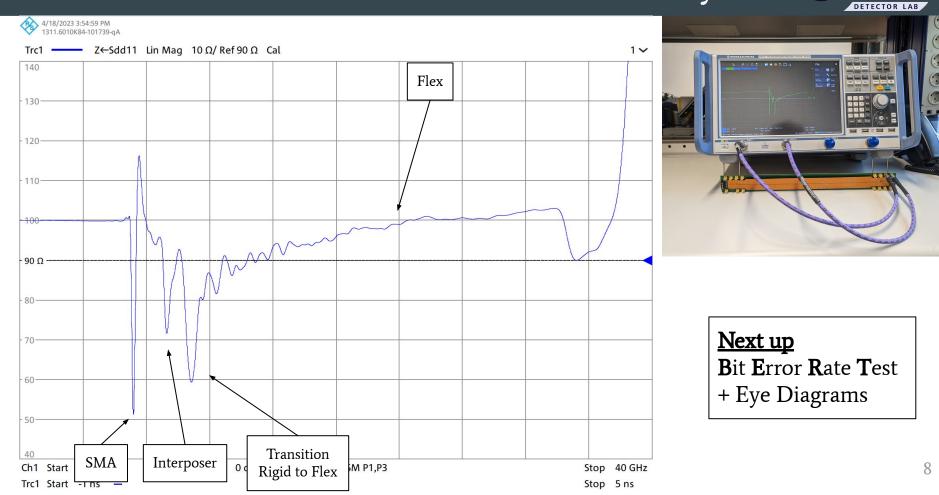


Time/Distance





PRîSM

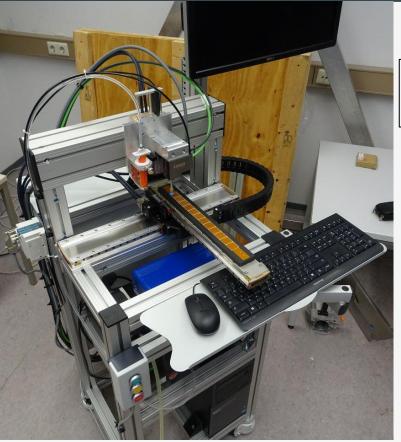


Gluing & Bonding of Sensors



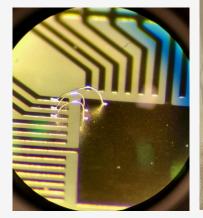
Gluing & Bonding

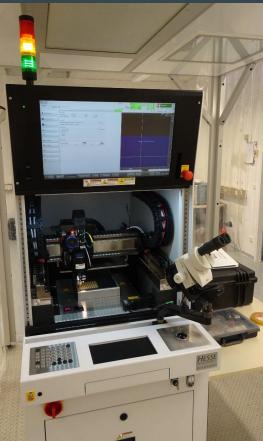




<u>Gluebot</u>

Production of all 260 strips in Mainz \rightarrow semi-automated processes

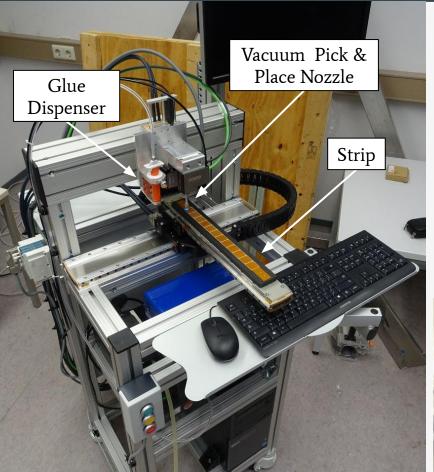




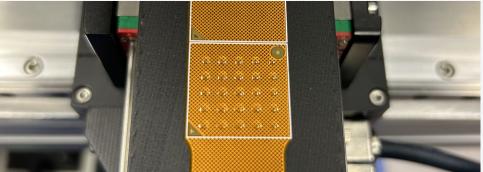
Wire-Bonding Machine 9

Gluebot

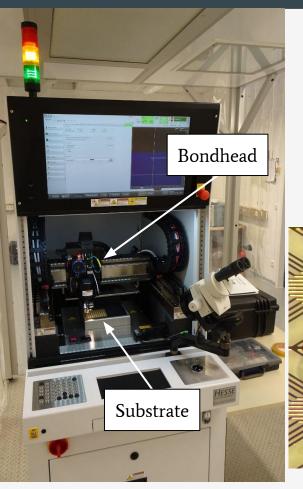




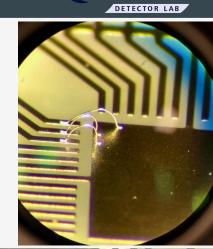
- Build & Developed by us
- Features
 - \circ 4 Axes CNC Machine
 - Vacuum Table
 - Time Pressure Dispenser
 - Vacuum Pick & Place Nozzle
 - Microscopic Camera
 - Laser Distance Sensor
 - UV LEDs for Curing
- Sensor Placement Precision Goal ~10 μm



Wire Bonding Machine



- Commercial Machine
- Ultrasonic Wedge Bonding (cold welding)
- Aluminium Wire 25 μm
- Pattern Recognition
- Speed ~3 wire bonds / s



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Conclusion & Outlook



<u>Rigid-Flex</u>

- Developing Testing Methods
- Time Domain Reflectometry for understanding
- Bit Error Rate Test & Eye Diagram (signal integrity)

Gluing & Wire Bonding

- Glue Dispensing & Wire Bonding parameters
- Gluebot Picking & Placing of Sensors
- Semi-automation of processes (pattern recognition etc.)



Conclusion & Outlook



Thanks for your attention!

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Gluing & Wire Bonding

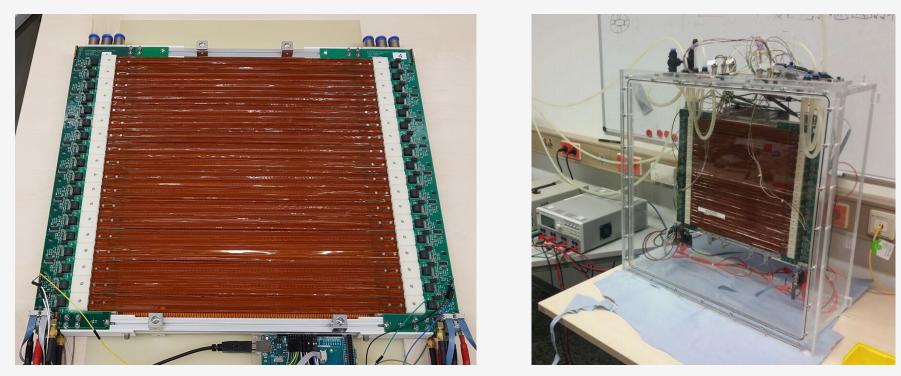
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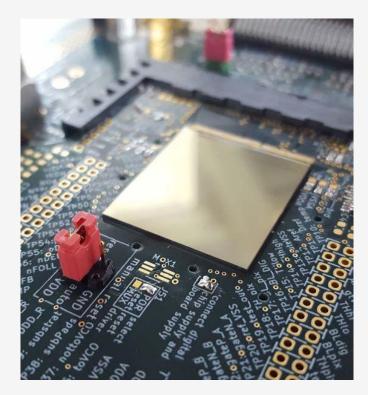
Thermo Mechanical Prototype



[Marco Zimmermann & Michail Kravchenko]

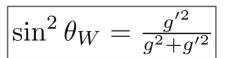
MuPix 10

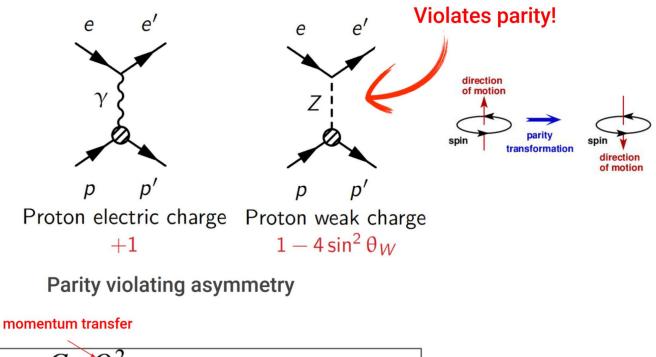
- HV-MAPS High voltage monolithic active pixel sensors (Ivan Perić)
- Based on 180 nm HV-CMOS process
- Can be thinned down to $50 \ \mu m$
- Pixel Matrix 256 x 250
- Pixel Size 80 μm x 80 μm
- Active Area 20.40 mm x 20 mm
- Efficiency > 99%
- Noise Rate < 2 Hz / Pixel
- Power Consumption < 200 mW / cm²



P2 - Theory

The weak mixing angle (Weinberg-angle):



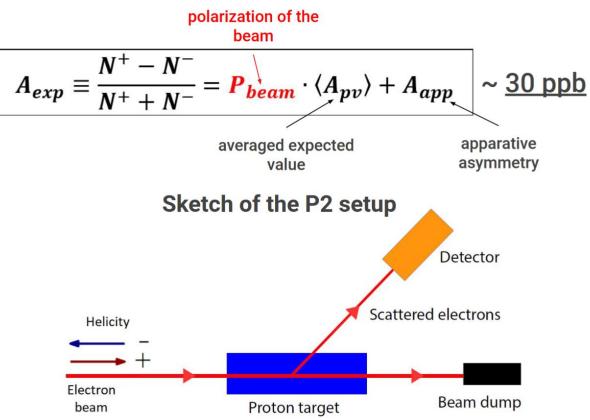


Asymmetry:
$$A_{PV} = \frac{G_F Q^2}{4\sqrt{2\pi}\alpha} \left(1 - 4\sin^2\theta_W - F(Q^2)\right)$$

proton form factor (small @ low Q²)

P2 - Experiment

Measuring the parity violating asymmetry in e-p-scattering



Beam:

- Highly polarized (≥85%)
- Current: 150 µA = 10¹⁵ e⁻/s
- $L \approx 2.4 \cdot 10^{39} \text{ cm}^{-2} \text{s}^{-1}$
- Energy: 155 MeV
- Flip helicity @ 1 kHz

Additional requirement:

Beam polarization: $\Delta P_b/P_b ≤ 0.5\%$

Characteristic Impedance

